

Slow entropy of some skew products

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<https://arxiv.org/abs/2506.17932>

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Disclaimer

In this talk all systems have discrete time \mathbb{Z} or \mathbb{N} (no flows)

Measurable dynamical system

Measure preserving transformation $T \curvearrowright (X, \mathcal{X}, \mu)$ on a probability space.

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Often they will be invertible, but not always

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- 3 Natural problem: how can we distinguish $S \rtimes_{\tau} T_1$ and $S \rtimes_{\tau} T_2$?
- 4 This problem is well-studied for measure preserving systems; we study it for topological systems.
- 5 We propose a solution based on slow entropy, an invariant introduced by Katok and Thouvenot.

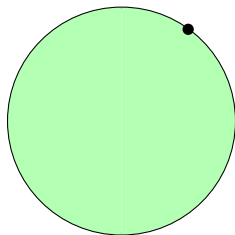
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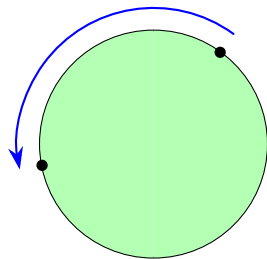
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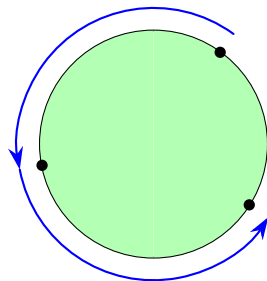
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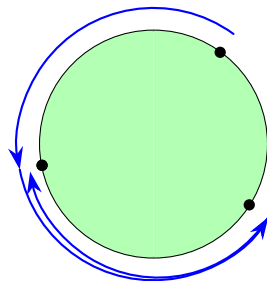
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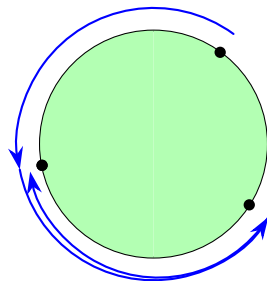
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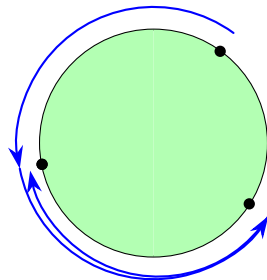
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For instance:



Take the space

$$\{-1, 1\}^{\mathbb{Z}} \times \mathbb{T}$$

and the transformation

$$(y, x) \mapsto (\sigma(y), T^{y(0)}(x))$$

The $[T, T^{-1}]$ system

The $[T, T^{-1}]$ system is the skew product

- Base: $\sigma \curvearrowright (\{-1, 1\}^{\mathbb{Z}}, \mu_{\frac{1}{2}, \frac{1}{2}})$
- Fiber: $T \curvearrowright (X, \mathcal{X}, \mu)$

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In 1982 Kalikow proved that if T has positive entropy, then $\sigma \rtimes T$ is K and not Bernoulli (first “natural” known examples).

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How can we distinguish these systems?

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One can prove that all of these systems have the same entropy

$$h_{\mu_{\frac{1}{2}, \frac{1}{2}} \times \mu}(\sigma \rtimes T) = h_{\mu_{\frac{1}{2}, \frac{1}{2}}}(\sigma) = \log 2$$

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$\sigma \rtimes T_1$ measurably isomorphic to $\sigma \rtimes T_2 \Rightarrow T_1$ and T_2 have the same entropy.

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Theorem (Austin 2015)

Yes.

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The new transformation is

$$S \rtimes_{\tau} T \curvearrowright (Y, \mathcal{Y}, \nu) \times (X, \mathcal{X}, \mu)$$

$$(y, x) \mapsto (S(y), T^{\tau(y)}(x))$$

What happens in the general case?

For which choices of $S \curvearrowright (Y, \mathcal{Y}, \nu)$ and $\tau: Y \rightarrow \mathbb{Z}$ is the entropy of the fiber an isomorphism invariant in the corresponding class of skew products?

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- 3 A mixing SFT $S \curvearrowright (Y, \mathcal{Y}, \nu)$, ν a Gibbs measure, and $\tau: Y \rightarrow \mathbb{Z}$ satisfying a technical condition (Austin 2015)

What happens in the general case?

For which choices of $S \curvearrowright (Y, \mathcal{Y}, \nu)$ and $\tau: Y \rightarrow \mathbb{Z}$ is it true that the fiber entropy is an isomorphism invariant in this corresponding class of skew products?

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- No known results with zero entropy systems in the base.
- What happens for topological systems?
- We propose a solution, it works for a diverse class of S and τ .

Topological skew products

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The new transformation is

$$S \rtimes_{\tau} T \curvearrowright Y \times X$$
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The problem

The class of systems

For fixed (Y, S, τ) , we consider the family of skew products $S \times_{\tau} T$, where (X, T) is an arbitrary invertible topological dynamical system.

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Determine if the entropy of the fiber T is an invariant for topological conjugacy within this class.

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Determine if ~~entropy~~ *entropy type* invariants of the fiber T are an invariant for topological conjugacy within this class.

Intuition

The problem is interesting when the entropy of the fiber “disappears”. Informally,

of (n, ϵ) -Bowen balls $\approx e^{n \cdot h_{\text{top}}(S) + f(n)h_{\text{top}}(T)}$
needed to cover the space

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Intuition

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We want to capture the contribution of $h_{\text{top}}(T)$ in this relation.

of (n, ϵ) -Bowen balls $:= \text{spa}(T, n, \epsilon)$ $n \in \mathbb{N}, \epsilon > 0$
needed to cover the space

Topological slow entropy

Definition (Katok and Thouvenot '97)

Let $\mathbf{a} = \{a_n(t)\}_{n \in \mathbb{N}, t > 0}$ be a family of sequences with

- for each n , $t \rightarrow a_n(t)$ is monotone,
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The upper slow entropy of (X, T) with scale \mathbf{a} is

$$\overline{\text{ent}}_{\mathbf{a}}(T) = \lim_{\epsilon \rightarrow 0} \overline{\text{ent}}_{\mathbf{a}}(T, \epsilon)$$

$$\overline{\text{ent}}_{\mathbf{a}}(T, \epsilon) = \sup(\{0\} \cup \{t > 0 : \limsup_{n \rightarrow \infty} \frac{\text{spa}(T, n, \epsilon)}{a_n(t)} > 0\})$$

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- With scale $\{n^t\}_{n \in \mathbb{N}, t > 0}$ we obtain the so called polynomial complexity or polynomial entropy of the system.

The main result

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Theorem (C, arXiv:2506.17932)

Let (Y, S) be a subshift and let $\tau: Y \rightarrow \mathbb{Z}$ be continuous. Then there is a scale \mathbf{a} depending only on (Y, S, τ) such that for every invertible topological dynamical system (X, T) we have

$$\overline{\text{ent}}_{\mathbf{a}}(S \rtimes_{\tau} T) = \underline{\text{ent}}_{\mathbf{a}}(S \rtimes_{\tau} T) = h_{\text{top}}(T),$$

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This shows that the entropy of the fiber is a conjugacy invariant in the corresponding class of skew products $S \rtimes_{\tau} T$.

A relative version of the main result

Theorem (C, arXiv:2506.17932)

Let (Y, S) be a subshift and let $\tau: Y \rightarrow \{-1, 0, 1\}$ be continuous. For every scale \mathbf{b} we can find a scale \mathbf{c} such that for every invertible topological dynamical system (X, T) we have

$$\underline{\text{ent}}_{\mathbf{b}}(T) \leq \overline{\text{ent}}_{\mathbf{c}}(S \rtimes_{\tau} T) \leq \overline{\text{ent}}_{\mathbf{b}}(T)$$

provided that τ satisfies the condition of being λ -unbounded for some $\lambda > 0$ (defined soon).

This shows that for any scale \mathbf{b} , the *slow entropy* with scale \mathbf{b} of the fiber is a conjugacy invariant in this class of skew products, but we must restrict to fiber systems with the property $\overline{\text{ent}}_{\mathbf{b}}(T) = \underline{\text{ent}}_{\mathbf{b}}(T)$.

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- For $y \in Y$ we interpret $N \rightarrow \sum_{n=0}^{N-1} \tau(S^n(y))$ as a walk on \mathbb{Z} , and we define the *range* $R_N(y)$ as the set of places in \mathbb{Z} it visits in N steps:

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Definition

Given a subshift (Y, S) and a cocycle $\tau: Y \rightarrow \mathbb{Z}$ depending only on the zero coordinate of the configuration, we say that τ is λ -unbounded ($\lambda > 0$) if for all $C \in \mathbb{N}$

$$\liminf_{n \rightarrow \infty} \frac{|\{w \in L_n(Y) : |R_n(w)| \geq C\}|}{|L_n(Y)|} \geq \lambda$$

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- If $R_n(y)$ unbounded for all y , then this holds.
- Also true for $(\{-1, 1\}^{\mathbb{Z}}, \mu_{\frac{1}{2}, \frac{1}{2}})$ and $\tau(y) = y(0)$.

Examples

Lets review some choices of (Y, S) and τ that have this property.

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(Y, S) is a minimal subshift and $\tau: Y \rightarrow \mathbb{Z}$ is not a coboundary (i.e. $\tau = g - g \circ S$ for some continuous $g: Y \rightarrow \mathbb{R}$).

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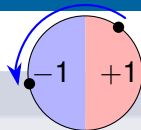
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- For any T we have $h_{top}(S \rtimes_{\tau} T) = h_{top}(S) + \alpha h_{top}(T)$, so applying the main theorem is an overkill.
- The conclusion of the “relative main theorem” is nontrivial: if T_1 and T_2 have zero entropy but different polynomial complexity ($\underline{\text{ent}}_{nt}(T_1) < \overline{\text{ent}}_{nt}(T_2)$), one obtains a scale for slow entropy that distinguishes $S \rtimes_{\tau} T_1$ and $S \rtimes_{\tau} T_2$.

Example

The deterministic random walk (the subshift copy).



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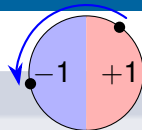
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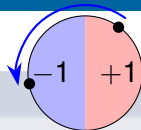
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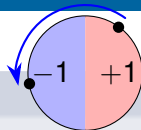




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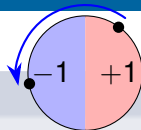
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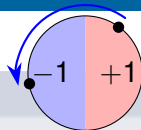
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- Here $h_{top}(S \rtimes_{\tau} T) = \log(2) + f(h_{top}(T))$, for some $f: [0, \infty) \rightarrow [0, \infty)$ strictly increasing.
- Applying the main theorem is an overkill.
- The conclusion of the “relative main theorem” is nontrivial: if T_1 and T_2 have zero entropy but different polynomial complexity ($\underline{\text{ent}}_{nt}(T_1) < \overline{\text{ent}}_{nt}(T_2)$), one obtains a scale for slow entropy that distinguishes $S \rtimes_{\tau} T_1$ and $S \rtimes_{\tau} T_2$.

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Take a topological system $T \curvearrowright (X, d)$.

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and

$$\text{spa}(T, F, \epsilon)$$

equals the minimal number of Bowen d_F, ϵ -balls needed to cover X .

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We can ignore the shape of $R_N(w)$ and only care about their cardinality. Remember that $\text{spa}(T, \{0, \dots, N-1\}, \epsilon) \approx e^{h_{\text{top}}(T)N}$.

$$\approx \sum_{w \in L_n(Y)} e^{|R_N(w)|h_{\text{top}}(T)}$$

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We have $\overline{\text{ent}}_{\mathbf{a}}(S \rtimes_{\tau} T) = h_{\text{top}}(T)$ because

- $t < h_{\text{top}}(T)$ implies $\sum_{w \in L_n(Y)} e^{|R_N(w)|t} \ll \sum_{w \in L_n(Y)} e^{|R_N(w)|h_{\text{top}}(T)}$
- $t > h_{\text{top}}(T)$ implies $\sum_{w \in L_n(Y)} e^{|R_N(w)|t} \gg \sum_{w \in L_n(Y)} e^{|R_N(w)|h_{\text{top}}(T)}$

General case

If τ takes values outside $\{-1, 0, 1\}$, the sets $R_N(w)$ may have holes, and this causes extra growth of $\text{spa}(T, R_N(w), \epsilon)$.

For instance, if $R_N(w) = \{2, 4, \dots, 2N\}$,

$$\text{spa}(T, R_N(w), \epsilon) \approx e^{2 \cdot h_{\text{top}}(T)N}$$

It is possible to quantify this extra contribution and include it to the scale, so that they “cancels out”.

Comments and questions

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The scales constructed here don't work for these purposes (in general).

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